

A Review on Reasons behind Failure of Helical Gear

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Abstract - Marine engines are heavy-duty machineries, which need to be sorted within the fine way for the duration of prototype development degrees. These engines are operated at very high speeds which consist of large stresses and deflections within the gears as well as in different rotating components. For the secure functioning of the engine, those stresses and deflections should be minimized. In this paper, Literature survey is finished on failure of gears occurred in reciprocating diesel engines & additionally on fatigue failure of gears. Together with this problem definition is proven to find out motives at the back of the failure of helical gear.

I. INTRODUCTION

Gears are most generally used for strength transmission in all the modern-day gadgets. Those toothed wheels are used to change the velocity or power between enter and output. They have won huge range of acceptance in all styles of applications & have been used drastically in the high speed marine.

Inside the present technology of sophisticated era, equipment layout has developed to an excessive degree of perfection. The layout and manufacture of precision cut gears, made from materials of excessive strength, have made it possible to supply gears which might be able to transmitting extraordinarily large masses at extraordinarily high circumferential speeds with very little noise, vibration and other unwanted components of equipment drives.

A gear is toothed wheel having a special teeth area of profile enabling it to mesh smoothly with different gears and power transmission takes location from one shaft to other via successive engagement of tooth.

Gears function in pairs, the smallest of the pair being known as 'pinion' & the larger one 'equipment'. Usually the drives the gear & the gadget acts as a pace reducer & torque converter.

A. Helical Gear

Helical gears provide a refinement over spur gears. The leading edges of the teeth are not parallel to the axis of rotation, but are set at an attitude. Since the tool is curved, this angling reasons the each form to be a segment of a helix. The angled teeth interact extra step by step than do spur gear teeth. This causes helical gears to run greater easily & quietly than spur gears. Helical gears also offer the opportunity of the use of non-parallel shafts.

With parallel helical gears, each pair of enamel first makes contact at a single point at one side of the tools wheel; a shifting curve of touch then grows step by step throughout the tooth face. it is able to span the complete width of the tooth for a time. Subsequently, it reduces until the enamel ruin contact at an unmarried factor on the opposite facet of the wheel. For that reason force is taken up & launched regularly.

B. Double Helical Gear

Double helical gears, additionally known as herringbone gears, overcome the trouble of axial thrust offered through single helical gears via having enamel that set in 'V' shape. Every gear in double helical equipment can be notion of as requirements, however reflect picture, helical gears stacked. This cancels out the thrust considering the fact that every half of the equipment thrust within the contrary direction. They can be directly interchanged with spur gears without any need for unique bearings.

II. LITERATURE SURVEY

The engine utilized in ninety nine% of contemporary ships is diesel reciprocating engines. The rotating crankshaft can power the propeller directly for slow speed engines, through a gearbox for medium and excessive speed engines, or through an alternator and electric powered motor in diesel-electric powered vessels. Diesel engines soon supplied more performance the helical gears are broadly used as power transmitting gears among parallel or crossed shafts, on the grounds that no longer best can they carry larger hundreds but additionally the dynamic load and the noise level skilled all through the operation is minimum.

A. Failure of gears

Gears can fail in many approaches and except for a boom in noise level and vibration, there's frequently no indication of issue till total failure happens. In preferred, every kind of failure leaves traits clues on equipment teeth, and distinct examination regularly yields enough statistics to establish the reason of failure. The overall kinds of failure modes include fatigue, impact fracture, wear and stress rupture, but for decades had an inferior strength to space ratio. Surface contact fatigue of equipment tooth is one of the maximum commonplace reasons of tools operational failure because of excessive neighborhood hertz on contact fatigue stresses. Usually, there are two kinds of surface contact fatigue, specifically pitting & Spaling. The pitting of gear is characterized by incidence of small pits on the touch floor. Pitting originates from small, surface or subsurface initial cracks, which grow beneath repeated contact loading. Spaling in standard is not considered a preliminary mode of failure but instead a continuation or propagation of pitting & rolling touch fatigue. Although pitting seems as shallow craters at contact surfaces, Spaling seems as deeper cavities at contact surfaces.

B. Fatigue failure of gear

Surface contact fatigue of tools enamel is one of the maximum commonplace causes of tools operational failure due to immoderate local Hertzian contact fatigue stresses. Helical gears are broadly used as strength transmitting gears among parallel or crossed shafts, due to the fact not only can they convey larger hundreds however also the dynamic load & the noise level skilled during the operation are minimum gears can fail in many extraordinary ways, and besides for an boom in noise level & vibration, there may be regularly no indication of issue until total failure happens. In popular, each sort of failure leaves feature clues on equipment teeth and unique exam often yields sufficient records to establish the motive of failure. The general forms of failure modes encompass fatigue, impact fracture, wear and pressure rupture. Fatigue is the maximum common failure in gearing. As current deliver propellers are at their most efficient at the outlet pace of the maximum gradual velocity diesel engines, ships with these engines do now not commonly need gearboxes. Typically, such propulsion systems includes either one or two propeller shafts every with its personal direct drive engine. Ships propelled by medium or high velocity diesel engines may have one or propellers, usually with one or extra engines driving each propeller shaft through a gearbox.

III. PROBLEM DEFINITION

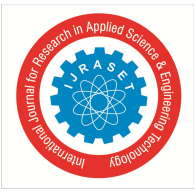
The engine used in ninety nine% of cutting-edge ships is diesel reciprocating engines. The rotating crankshaft can strength the propeller immediately for sluggish pace engines, through a gearbox for medium and high pace engines, or thru an alternator and electric motor in diesel electric powered vessels. The reciprocating marine diesel engine first came into use in 1903 while the diesel electric river tanker Vandal turned into put in service by means of Bramble. Diesel engines soon presented greater performance than the steam turbine, but for decades had an inferior power to area ratio.

As space better up in passenger ships & ferries is at premium; these ships have a tendency to apply multiple medium speed engines ensuing in longer, lower engine room than that wished for two-stroke diesel engines. More than one engine installations additionally provide redundancy in the occasion of mechanical failure of 1 or more engines and a extra performance over a wide a number of operating conditions. Helical gears are commonly used in industry & their touch behavior merits greater interest to set up a practical base for the designated study of gear fraction, wear and existence. The tools contact stresses derived from the teeth contact forces and geometry are very essential for determining equipment pitting, i.e. lifestyles performance. Tooth contact forces along the line of action depend basically on load sharing between meshing teeth & therefore a sensible evaluation of helical equipment touch additionally calls for facts on structural deformations, which include tooth deflection. Destructive pitting & spalling had been also cited on the lively facet of each enamel at one quit of teeth on the pitch line. Detrimental pitting seems as much larger pits than initial pitting. Those larger craters typically are as a result of more intense overload conditions. Spalling is similar to negative pitting besides that the pits are normally larger in diameter & quite shallow. Frequently the spalled area does no longer have a uniform diameter. A spalling hollow space consists of a shallow wall and a steep wall. Both the shallow & steep wall has jagged surfaces. It originates below the surface, generally at or close to the case/ core transition sector. Spalling is caused by excessively excessive touch stresses. Typically, large pits are fashioned; due to the fact pressure tiers are high, the rims of the preliminary pits smash away swiftly and massive abnormal voids are shaped.

IV. CONCLUSION

Reasons behind the failure of helical gear

- A. Use of incorrect materials
- B. Spaling is usually caused by excessively high contact stresses



- C. Seeded defect on tooth due to high speed of helical gear
- D. Failure like holes drilled on helical gear teeth face.

The failed helical equipment had some of adjoining teeth and random teeth breakage at one cease of tooth. An assessment of the failed helical equipment become undertaken to assess its integrity that included a visible examination, photograph documentation, chemical analysis, micro-hardness size.

Enamel bending and floor touch is of the most commonplace modes of failure in gears. Numerous reasons of failure have been recognized. Those consist of bad design of gear set, incorrect meeting or misalignment of the gears, overloads, inadvertent strain raisers or subsurface defects in vital areas, & the usage of wrong substances.

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