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Simulation of CANINE: An Autonomous Quadruped Walking Robot in MATLAB –

Simscape Multibody

It is here by certified that the paper ID : IJRASET27949, entitled

by

Mrs. Priyanka Deshmukh

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ISRA Journal Impact Factor: **7.429** 





THOMSON REUTERS Researcher ID: N-9681-2016





after review is found suitable and has been published in Volume 8, Issue IV, April 2020 in

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