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International Journal For Research in  
Applied Science and Engineering Technology



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# **INTERNATIONAL JOURNAL FOR RESEARCH**

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

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**Volume: 9      Issue: XII      Month of publication: December 2021**

**DOI: <https://doi.org/10.22214/ijraset.2021.39350>**

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The circuit is composed of a DC to DC converter, a super capacitor, a solar panel, and the Li-ion battery.  $T_1 \sim T_4$  are the four IGBT switches and its corresponding diodes  $D_1 \sim D_4$  and an integrating magnetic structure with self-inductance  $L_1$ ,  $L_2$  and mutual inductance  $M$ , shares a core inductor. The solar panel provides current when solar radiation is available to the system with the battery charging when it is idle, the super capacitor controls the instantaneous state of peak power supply. The controller of the EV ensures the flow of electrical energy according the input from the solar panel and battery to the load motor.

### III. DESIGN AND INTEGRATION OF SOLAR PANEL WITH DC TO DC CONVERTER AND INTEGRATED MAGNETIC STRUCTURE

#### A. DC to DC Converter with Integrated Magnetic structure.

The magnetic elements are the main components of the energy conversion, filtering of harmonics from system, and energy storage. An E-type magnetic core is used in this converter. Here a coupling inductance ( $L_1$  and  $L_2$ ) is used, shown in Fig.2.  $L_2$  is the output filter and  $L_1$  is the external inductance, and  $C_a$  is additional capacitance. In the steady state, voltage of  $C_a$  is equal to the output voltage of  $L_2$  and  $L_1$  without regard to the voltage ripples of capacitor. The DC/DC converter of Fig.1 consists of 4 IGBT switches ( $T_1 \sim T_4$ ) and 4 diodes ( $D_1 \sim D_4$ ). As a boost converter we observe two operational modes (consisting of  $L_1$ ,  $T_4$ ,  $D_4$  or  $L_2$ ,  $T_2$ ,  $D_1$ ); and as buck converter three operational modes (consisting of  $L_1$ ,  $T_3$ ,  $D_4$  or  $L_2$ ,  $T_1$ ,  $D_2$ ).

There are 5 operating modes due to the additional battery pack change. This operating modes are parking charging mode, constant speed mode, acceleration mode, braking mode, super-capacitor charging mode. Table 1 shows the specific operation mode.

#### B. Integration of Solar Panel to the Charging System.

The solar panel setup is integrated to the charging system after the DC filter of the AC-DC converter. The output of the solar panel is not constant, as it is dependent on the solar radiation. To get constant output from the solar panel, the solar panel is controlled and optimized based on algorithm control. A perturb and observe (P & O) method is used in MPPT algorithm to control the output power and voltage from the solar panel setup. Fig.3 gives the simulation diagram of integration of solar panel to the system.

Table 1 Operating modes of energy storage system

| Working mode                  | Power sources            | Power flow                    | Operation mode |
|-------------------------------|--------------------------|-------------------------------|----------------|
| Parking charging mode         | AC power and solar power | Battery and super capacitor   | Buck           |
| Constant speed mode           | Battery                  | DC motor                      | Boost          |
| Acceleration mode             | Super capacitor          | DC motor                      | Boost          |
| Braking mode                  | Braking energy           | Battery and super capacitor   | Buck           |
| Super capacitor charging mode | Battery                  | Super capacitors and DC motor | Boost or Buck  |

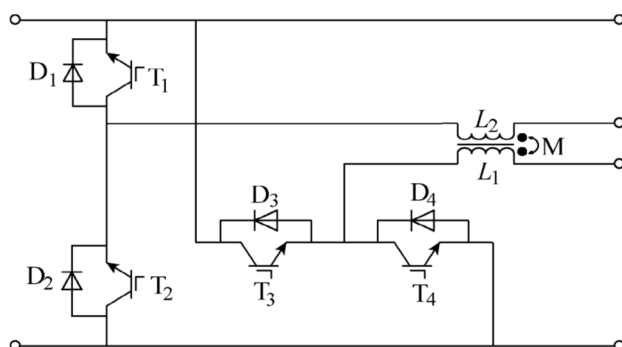
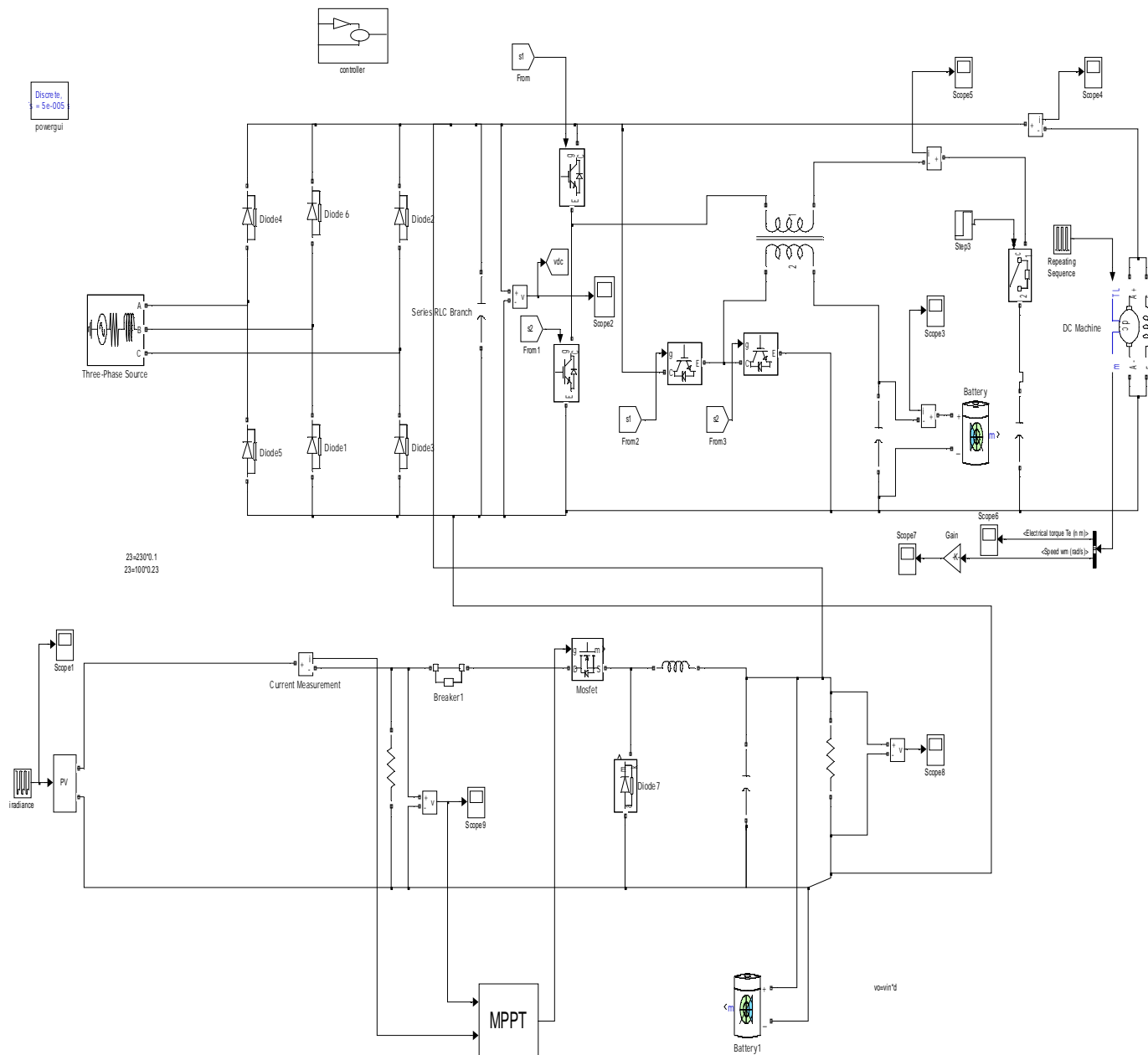


Fig.2 Topology of DC to DC converter with integrated magnetic structure.



### B. Li-ion Battery

Some deterioration occurs on each charge–discharge cycle. Degradation usually occurs because electrolyte migrates away from the electrodes or because active material detaches from the electrodes. Low-capacity NiMH batteries (1,700–2,000 mAh) can be charged 1,000 times, whereas high-capacity NiMH batteries (above 2,500 mAh) last up to 500 cycles. NiCd batteries can be used up to 1,000 cycles before their internal resistance permanently increases where its resistance goes beyond usable values. There are no ideal contenders for the electric vehicles, and Li-ion becomes a good choice. Li-ion batteries have higher energy density than lead-acid batteries or nickel-metal hybrid batteries, so it is possible to make battery size smaller than others while retaining same storage capacity. The weight of Li-ion battery is 50-60% less weight than lead-acid equivalent. It has the longest life, more usable capacity, temperature tolerant. A discrete PI controller is designed to the system to control the charging and discharging of battery and the super capacitor. Fig.4 shows the controller used for battery and super capacitor.

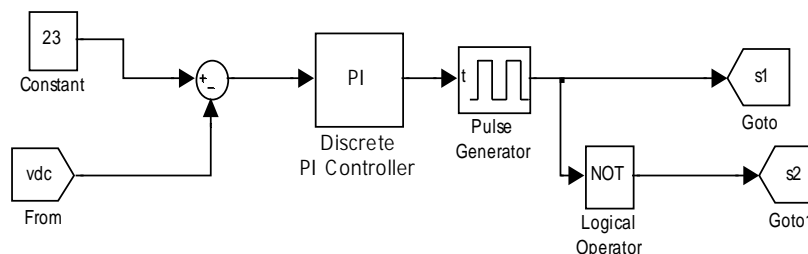


Fig.4 Controller for the DC-DC converter, battery and super capacitor.

Assuming a loss less converter, the dc motor current is equal to the battery current, and is expressed as:

$$V_{load} \times I_{load} = V_{batt} \times I_{batt}; \quad (1)$$

$$I_{batt} = \frac{V_{load} \times I_{load}}{V_{batt}} \quad (2)$$

The reference current of the battery pack is expressed as:

$$I_{batt}^* = \frac{V_{load} \times I_{load}}{V_{batt}} G_{lp}(s) \quad (3)$$

Where  $V_{load}$  and  $I_{load}$  stands for the voltage and current of DC motor;  $V_{bat}$  and  $I_{bat}$  are the voltage and current of Li-ion battery.

$G_{lp}(s)$  is the transfer function of Bessel low-pass filter which can be expressed as:

$$G_{LP}(s) = \frac{\theta_n(0)}{\theta_n(s/\omega_0)} = \frac{b(1)s^n + b(2)s^{n-1} + \dots + b(n+1)}{s^n + a(2)s^{n-1} + \dots + a(n+1)} \quad (4)$$

$\theta_n(s)$  is the reverse bessel polynomials,  $\omega_0$  is the cutoff frequency,  $a(n)$  and  $b(n)$  are coefficient of the bessel polynomials.

The Bessel filter is a linear filter with largest flat group delay or linear phase response and can fully retain a filtered waveform and maintain a stable group delay. Once the battery output reference current is established, the converter is controlled by the peak current controller.

### C. Continuous Charging Of Super Capacitor From Battery

The super capacitor charges from battery when the SOC of super capacitor is below the limit to ensure the enough energy supply from the super capacitor. A target value is set as the initial value to provide enough energy. During driving and standstill to recharge the super capacitor an PI controller is designed.

### D. Control of PV Panel Output

The maximum power supplied by the photovoltaic panels is not always stable and fixed in same operating point; it varies with weather conditions, such as solar radiation, shadow, and temperature. To extract the maximum power, it is very necessary to implement an MPPT algorithm that dynamically adjusts the extraction of power from the PV panel. Convergence speed is one of the most important features of all different algorithms. Any improvement in the rise time of MPPT improves reliability of the system and increase the power extraction and efficiency of the whole system.



Herein a MPPT (Maximum Power Point Tracking) algorithm is used to generate a constant output from the PV panel. There are different types of MPPT algorithm

- 1) Perturb and Observation (P&O)
- 2) Incremental conductance (IncCond)
- 3) Ripple correlation

Perturb and observe algorithm is a simple among all and does not require any previous knowledge of the PV generation characteristics or measurement of solar intensity and cell temperature and it is easy to implement with analog and digital circuits. Flow chart of perturbation and observation is shown in Fig.5. This method basically uses the controlling of duty cycle based on power and voltage receiving from the photo voltaic panels.

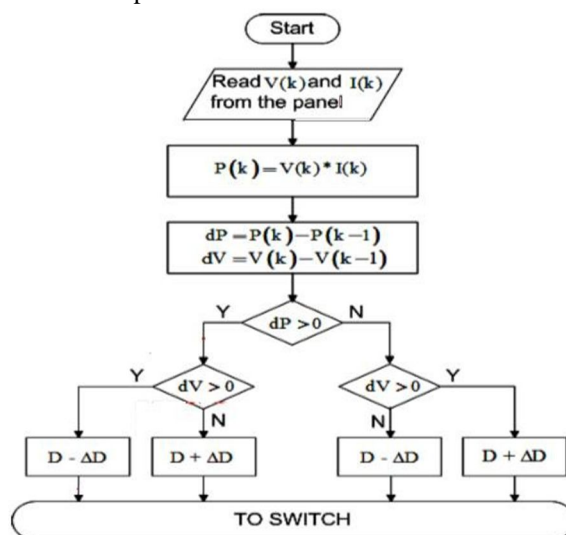


Fig.5 Flow chart of MPPT perturb and observe method.

## V. SIMULATION OF PV BASED HESS APPLIED ON ELECTRIC VEHICLE

A basic electric vehicle model was created with simulink and simulation was performed. The simulation of cars during the acceleration mode, constant speed mode, braking mode, and parking charging mode are built on matlab/simulink, and the load side voltage, battery and super capacitor current ripples are observed.

The ripples of the battery and the load are mostly negligible, due this ripple reduction of battery and the load, a smooth and slow ramop operation is obtained. The super capacitor recovers the braking energy, where as the battery pack as single storage is responsible to set change in the load and has high fluctuations and ripple in current, which will reduce the overall life of battery, which is not suitable to electric vehicle.

Fig.6 shows the waveforms of battery when no super capacitor is connected and Fig.7 shows the waveform of battery with the super capacitor connected in it. There is reduction of ripples in the battery current and as well as in load current. The super capacitor takes the large current ripples from the system.

Fig.8 shows the simulation of the battery when a PV panel is integrated with system, it is observed that the overall performance of this system is improved. Compared to current of super capacitor, battery current fluctuations are smoother with no instantaneous perturbations. The output of battery is smooth and it has a minimal ripple content, which extends the life of the battery and can reduces the loss due to ripple content caused by DC motor. A sudden change in current of the super capacitor is normal as it is absorbing high frequency contents of the load. The fluctuations in load are due to the acceleration and braking of the vehicle. Load side current, battery, super capacitor current ripples are observed.

Fig.9 to Fig.11 shows the zoomed output waveforms of battery when it is not connected to super capacitor, when it is connected to super capacitor, and when the HESS is integrated with solar energy system. Fig.12 and 13 shows the load current of the system, and Fig.14 and 15 shows the super capacitor currents. In Fig.9 there is a sudden step from a nominal value to high, where as in Fig.10 the battery with super capacitor has smooth current with controlled ramop and with some ripples with it. The integration of solar energy system the battery current ripples are reduced with maintaining the smooth controlled ramop which is shown in Fig.11.

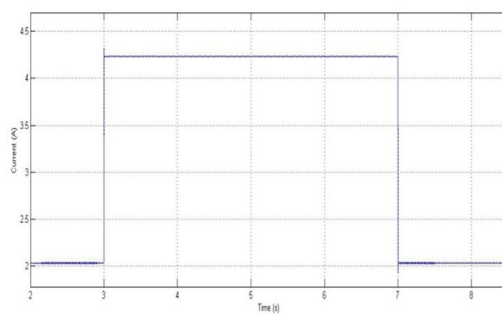


Fig.6 Battery output without super capacitor.

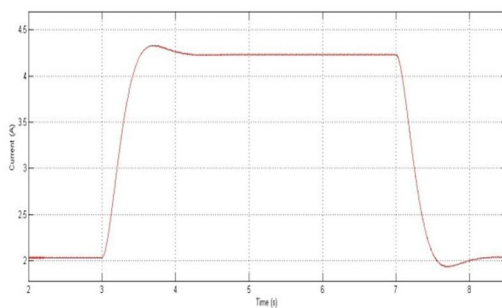


Fig.7 Battery output with super capacitor.

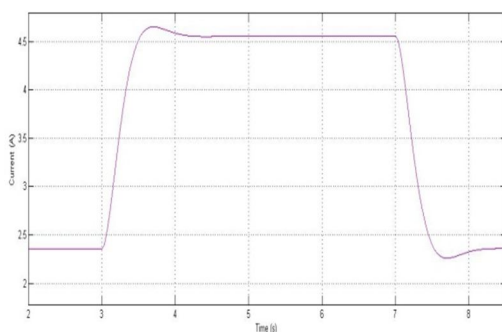


Fig.8 Battery output after adding PV-panel to the HESS

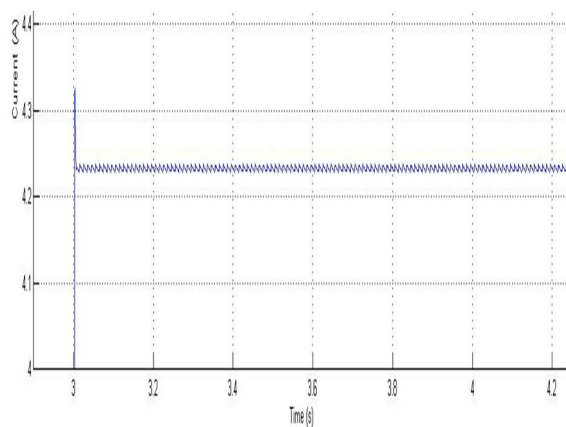


Fig.9 Battery output without super capacitor.

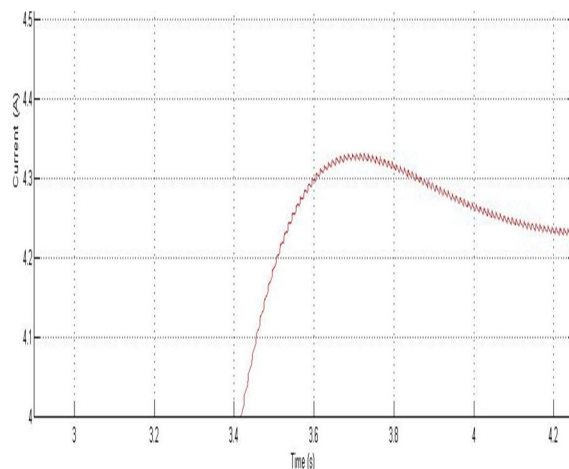


Fig.10 Battery output with super capacitor.

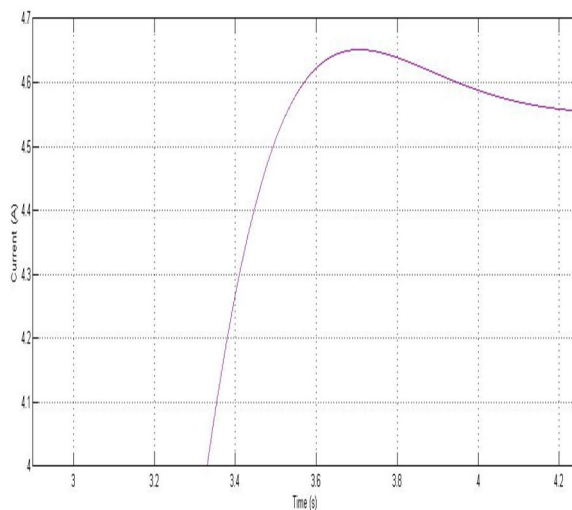


Fig.11 Battery output with integrated PV system.

## VI. CONCLUSION

A PV based HESS is designed for electric vehicle based on limitations of battery and a solar energy system is added to the HESS. The proposed system is compared with the HESS, and shows a good advantage of increasing the battery performance and giving an advantage of charging the EV while parking with reduced ripple contents in the output current which in result increasing the battery life.

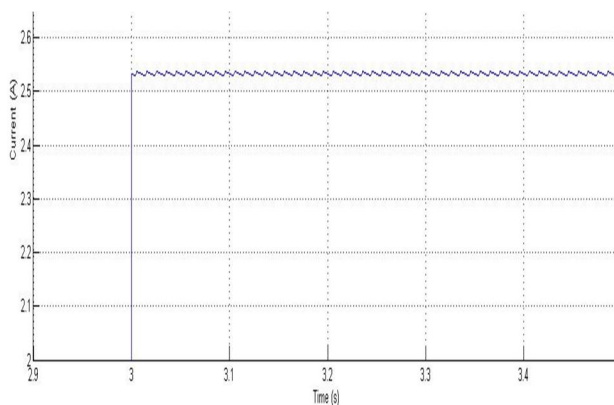


Fig.12 Load current with super capacitor.



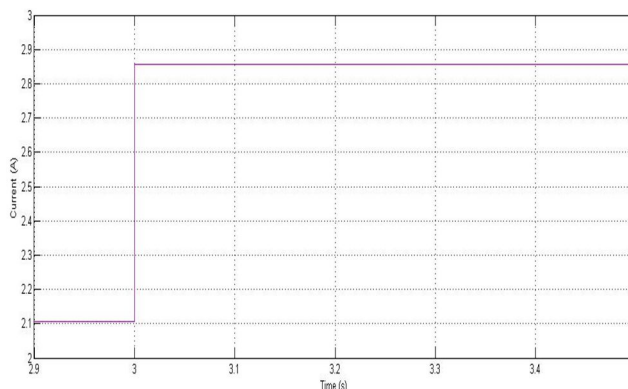


Fig.13 Load current with integrated PV system.

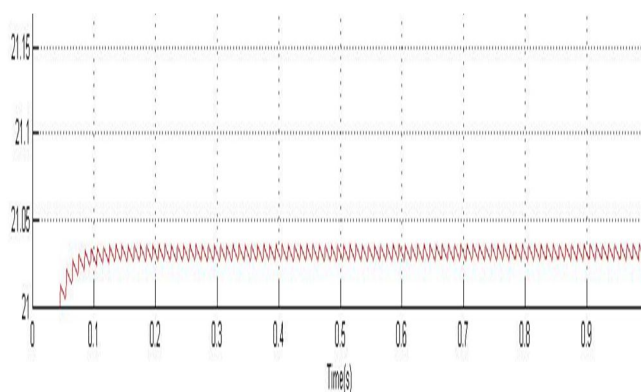


Fig.14 Super capacitor current of HESS.

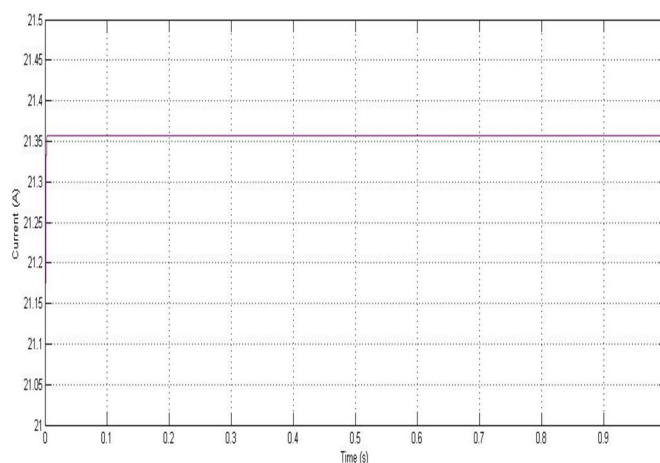


Fig.15 super capacitor current of integrated PV system.

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