



IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Volume: 12 Issue: XI Month of publication: November 2024 DOI: https://doi.org/10.22214/ijraset.2024.65544

www.ijraset.com

Call: 🕥 08813907089 🔰 E-mail ID: ijraset@gmail.com



## Safe Rider: Helmet Detection Using Machine Learning and Open CV

Tanmayee Godbole<sup>1</sup>, Purva Sapkal<sup>2</sup>, Sujal Malapure<sup>3</sup>, Shrihari Ganbavale<sup>4</sup>

Department of Electronics and Telecommunication Engineering, Vishwakarma Institute of Information Technology, Pune

Abstract: In India, many motorcyclists frequently violate traffic rules by not wearing helmets, and enforcement by traffic police is often limited due to the demanding nature of manual monitoring. Helmet detection is a crucial aspect of ensuring road safety, particularly for motorcyclists. Non-compliance with helmet regulations can lead to severe injuries and fatalities in the event of accidents. This paper presents an intelligent system for automatic helmet detection using a combination of OpenCV for image processing and machine learning algorithms for classification. The proposed system utilizes real-time video feed or static images to detect and identify whether a person is wearing a helmet, aiming to automate helmet compliance checks in traffic surveillance environments. This automated helmet detection system has the potential to enhance traffic law enforcement and reduce human intervention, leading to safer road environments.

Keywords: Helmet Detection, Number Plate Detection, Image Processing, Open CV

#### I. INTRODUCTION

In today's world, ensuring safety has become more critical than ever, especially in high-risk environments such as construction sites, factories, and roadways. Implementing safety protocols, like wearing helmets, is vital to protect individuals from potential hazards. However, manual enforcement of these measures can be inefficient and prone to human error. The Helmet Detection System, powered by Python, OpenCV, and the YOLOv5 (You Only Look Once) object detection algorithm, presents a highly efficient and intelligent solution.

This system leverages advanced computer vision techniques to automatically identify whether individuals in a scene are adhering to safety regulations by wearing helmets. The integration of YOLOv5, known for its real-time object detection capabilities, ensures that the system is not only fast but also highly accurate, capable of processing both static images and real-time video streams. By utilizing OpenCV's image processing capabilities, the Helmet Detection System can be deployed across various platforms, making it adaptable for different environments.

Processing significant amount of information in a time constraint manner is a challenging task. As such applications involve tasks like segmentation, feature extraction, classification and tracking, in which a significant amount of information need to be processed in short duration to achieve the goal of real-time implementation.

The combination of machine learning and OpenCV in helmet detection ensures accuracy and scalability, offering a solution that not only enhances safety compliance but also reduces human effort and error in the process.

This technology enhances safety protocols by providing automated monitoring and immediate feedback, reducing the dependency on manual supervision and significantly improving compliance rates. Its scalable nature ensures that it can be implemented in diverse settings, providing a proactive approach to safety that minimizes risks and protects lives.

#### II. LITERATURE SURVEY

Madhuchhanda Dasgupta, Oishila Bandyopadhyay, Sanjay Chatterji, Computer Science & Engineering IIIT Kalyani West Bengal, India," Automated Helmet Detection for Multiple Motorcycle Riders using CNN"[1]. Dasgupta emphasized that a key component of an efficient traffic management system lies in its capacity to continuously oversee vehicle compliance with traffic laws. In densely populated urban regions of India, motorcycles often serve as a primary mode of transportation. However, the study observed that a significant portion of motorcyclists tend to avoid securing basic insurance for city commuting or even everyday street use, highlighting a critical gap in traffic safety and regulation adherence.

A helmet is crucial for protecting the head, one of the most delicate parts of the human body. It should be mandatory for all motorcyclists, as motorcycle accidents frequently result in severe head injuries. Wearing a helmet can be a simple yet life-saving measure.



### International Journal for Research in Applied Science & Engineering Technology (IJRASET)

ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538 Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

To enhance the safety of motorcyclists in Surat, the Surat Municipal Corporation (SMC) took a significant step by implementing a real-time CCTV surveillance system, a pioneering initiative in India. Launched in 2015, the system was equipped with 297 cameras, managed through a centralized command and control centre, aimed at monitoring traffic compliance and enhancing road safety [2]. The growing concern of increased accidents and injuries associated with motorcycle use, partly due to the non-compliance of motorcyclists in wearing helmets. The surge in motorcycle traffic has made it harder to maintain road safety, and one of the key factors is the failure to wear helmets, which leads to more severe injuries in case of accidents. Currently, to enforce helmet-wearing laws, authorities rely on manual checks or video surveillance footage from cameras placed at intersections.

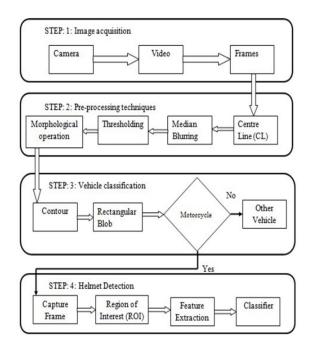
These methods are labour intensive, time-consuming, and prone to errors, as they require human observation to spot violations. The proposed solution is a computer-based design that can analyze images, potentially from surveillance cameras, to automatically detect individuals riding motorcycles without helmets. This system would improve the accuracy and efficiency of identifying motorcyclists who are not complying with helmet regulations, helping to enhance road safety.

The system processes moving objects and classifies them as either motorcycles or other types of moving vehicles, based on features extracted from their regional properties. This classification is carried out using the K- Nearest Neighbour (KNN)algorithm. The KNN classifier helps identify motorcycles by analyzing key characteristics of the object's movement and shape.[3]

However, a notable limitation of this system is that the motorcycle is only detected from a side view, making it impossible to capture or recognize the number plate. As a result, the system cannot officially identify the violator, limiting its effectiveness in enforcement actions. Vehicle classification into categories such as cars, motorcycles, trucks, etc., is performed using various methods. In this paper, \*\*SURF (Speeded-Up Robust Features), HAAR-like features, HOG (Histogram of Oriented Gradients), and LBP (Local Binary Patterns)\*\* are utilized as descriptors for feature extraction from vehicles. These descriptors help in identifying key features necessary for distinguishing between different vehicle types[4].For classification, advanced algorithms like \*\*Multilayer Perceptron (MLPs), Support Vector Machines (SVMs),\*\* and \*\*Radial Basis Function Networks (RBFNs)\*\* were employed. These classifiers enable precise categorization of vehicles based on the extracted features.

#### III. METHODOLOGY

This paper aims to propose a system for detection of motorcyclist without helmet. The system detects motorcyclists not wearing helmets and retrieves their motorcycle number plate in real time from videos captured by CCTV cameras at road junctions by making use of Machine Learning. The algorithm for a system that combines helmet and number plate detection using Open CV starts by capturing an image or video frame of a person riding a motorcycle. The image or video frame is then pre-processed using Open CV to enhance the quality of the image and reduce noise.





ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538 Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

The whole part is divided into 4 important parts as follows:

- 1) *Image Acquisition:* The process begins with cameras capturing images or video of traffic on public roads. These cameras can be strategically placed at intersections or along highways to gather data continuously.
- 2) *Preprocessing Techniques:* Captured images undergo preprocessing to enhance their quality for analysis. Techniques include noise reduction to eliminate random variations, contrast enhancement to highlight important features, and edge detection to identify the boundaries of objects. These steps prepare the images for better feature extraction and subsequent classification.
- 3) Vehicle Classification: In this stage, the system classifies vehicles using machine learning algorithms like Convolutional Neural Networks (CNNs) or Support Vector Machines (SVMs). These algorithms analyze features such as shape, size, and contour to differentiate motorcycles from other vehicles, ensuring accurate identification.
- 4) *Helmet Detection:* Once a motorcycle is detected, the focus shifts to the rider's head area to check for helmet compliance. This is achieved using object detection models, such as YOLO (You Only Look Once), which can identify whether a helmet is present. If the system detects that the rider is not wearing a helmet, it flags the incident for potential enforcement.

The object detection is been done with YOLO which a method / way to do object detection. It is the algorithm /strategy behind how the code is going to detect objects in the image. YOLO takes entirely different approach. It looks at the entire image only once and goes through the network once and detects objects.

#### A. Object detection using python and OpenCV

The DNN (Deep Neural Network) module, which was originally part of the opencv\_contrib repository, has been integrated into the main OpenCV repository as of last year. This enhancement allows users to perform inference on pre-trained deep learning models directly within OpenCV. Initially, the module supported only Caffe and Torch models, but it has since expanded its capabilities to include compatibility with additional frameworks, such as TensorFlow, thereby broadening its usability for developers and researchers in the field. The feeding of the video to the ML model is done using OpenCV for preprocessing and capturing of input is occurred frame by frame with the help of OpenCV tools. Firstly, resizing of the frames into the required resolution of 1920×1080p is done. Then the frame is fed as input to the neural network created using the TFNet function available with DarkFlow.

- 1) Software Requirements
- Python
- Anaconda
- 2) Hardware Requirements
- Processor : Intel Core i5
- RAM:8GB
- OS : Windows

#### 3) Libraries used

- ✓ Numpy- NumPy is a foundational library in Python, widely used for numerical computing. In the context of a helmet detection system, which typically involves computer vision and machine learning, NumPy plays a crucial role in handling the underlying data structures and operations. NumPy provides powerful tools for creating and manipulating large arrays and matrices, which are the core data structures in image processing. NumPy can easily handle such inputs, facilitating batch processing and efficient data feeding into the model.
- ✓ OpenCV- OpenCV (Open Source Computer Vision Library) is widely used in computer vision tasks, including helmet detection systems. OpenCV is primarily used for reading, processing, and displaying images and video streams, which are essential for detecting helmets in real-time or from recorded footage. It supports multiple file formats and camera input. For real-time helmet detection, OpenCV handles frame capture from a camera, processes the image in real-time, and draws bounding boxes around detected helmets. OpenCV allows for drawing bounding boxes and annotations on detected helmets, visualizing results in real-time, or saving them for further analysis.
- ✓ Pandas- While Pandas isn't directly used for image processing like NumPy, it plays an important role in handling the structured data that accompanies the detection process. Pandas is excellent for tasks like cleaning and preprocessing annotation files (e.g., CSV files) that contain information about where helmets are located in an image. After running the detection system, you may want to analyze the performance—such as the number of helmets detected correctly or missed.



ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538 Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

Pandas helps in summarizing and visualizing this data, enabling you to calculate metrics like accuracy, precision, and recall. If the system processes data in real-time or in batches, Pandas can store logs of detection results (e.g., timestamps, image paths, detection scores) to track the system's performance over time.

- 4) Algorithm
- ✓ Input Data Processing
- ✓ Object Detection Model
- ✓ Post Processing
- ✓ Helmet Detection
- ✓ Real time processing
- ✓ Performance Monitoring and alerts

#### 5) YOLO (You Only Look Once)

YOLO was proposed by Joseph Redmond et al. in 2015. It was proposed to deal with the problems faced by the object recognition models at that time, Fast R-CNN is one of the state-of-the-art models at that time but it has its own challenges such as this network cannot be used in real-time, because it takes 2-3 seconds to predicts an image and therefore cannot be used in real-time.[5]Whereas, in YOLO we have to look only once in the network i.e. only one forward pass is required through the network to make the final predictions. YOLO's real-time object detection capabilities have been invaluable in autonomous vehicle systems, enabling quick identification and tracking of various objects such as vehicles, pedestrians [6], bicycles, and other obstacles [7]. These capabilities have been applied in numerous fields, including action recognition [8] in video sequences for surveillance ,sports analysis, and human-computer interaction [9]. YOLO models have been used in agriculture to detect and classify crops [10], pests, and diseases , assisting in precision agriculture techniques and automating farming processes. They have also been adapted for face detection tasks in biometrics, security, and facial recognition systems [11].

#### IV. FUTURE SCOPE

This project can be used to implement an automatic challan system. The Helmet Detection system can be interfaced to motorcycles. Doing this we can control the Bike condition based on Helmet Detection. If Helmet is detected initially then the bike can turn ON. Else the bike cannot turn ON.

- 1) Smart Cities & IoT: Integrating helmet detection with smart cameras and IoT for real-time monitoring, issuing automatic alerts, and improving public safety in cities or construction sites.
- 2) *Better AI Models:* Using more advanced models for higher accuracy and expanding detection to other safety gear (like vests or gloves) for complete workplace safety solutions.
- *3) Edge Computing:* Deploying the system on small, efficient devices (like Raspberry Pi) for real-time detection without relying on the cloud.
- 4) Larger Scale Use: Applying the system to monitor traffic, collect data, and help reduce accidents. Cloud integration can help track helmet usage trends across regions.
- 5) *Privacy & Ethics:* Ensuring privacy by anonymizing faces, and complying with data protection laws to prevent misuse of surveillance data.
- 6) *Regulations & Compliance:* Partnering with governments to make helmet detection a safety standard and helping companies ensure compliance to lower insurance risks.

#### V. RESULTS

The helmet detection system successfully identifies individuals wearing or not wearing helmets in images or video streams. By using a pre-trained machine learning model integrated with OpenCV for image processing, the system accurately detects helmets in real-time with a high confidence scoreThe system's performance demonstrates reliability in diverse environments like traffic and construction sites, with potential for further scalability and integration into real-world safety applications.

#### VI. CONCLUSION

In conclusion, a helmet detection system using machine learning and OpenCV offers an effective solution for enhancing safety in various environments, such as roads and construction sites. By leveraging advanced image processing and AI models, the system can detect helmet usage in real time, helping to prevent accidents and ensure compliance with safety regulations. With its potential for integration into smart cities, IoT, and edge devices, this system can play a crucial role in improving public safety and reducing injuries through automation and advanced analytics.

International Journal for Research in Applied Science & Engineering Technology (IJRASET)



ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538 Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

#### REFERENCES

- M. Veldurthi and A. D. Dharmavaram, "Automatic Vehicle Identification and Recognition using CNN Implemented on PYNQ Board," 2022 6th International Conference on Electronics, Communication and Aerospace Technology, Coimbatore, India, 2022, pp. 1302-1306, doi: 10.1109/ICECA55336.2022.10009054.
  India mission smart cities: Surat: pdf available at
- "http://smartcities.gov.in/writereaddata/winningcity/SCP\_%20SURAT.pdf"
- [3] Waranusast, N., Bundon, V., Timtong, N., Tangnoi, C., & Pattanathaburt, P. (2016). Machine vision techniques for motorcycle safety helmet detection. In 2016 28th International Conference on Image and Vision Computing (IVCNZ), New Zealand, 2016.
- [4] Silva, R., Romuere, et al. (2016). Automatic Motorcycle Detection on Public Roads. CLEI Electronic Journal, Vol. 19, No. 1, pp. 70-77. ISSN: 1390-8773.
- [5] J. Redmon, S. Divvala, R. Girshick, and A. Farhadi, "You only look once: Unified, real-time object detection," in Proceedings of the IEEE conference on computer vision and pattern recognition, pp. 779–788, 2016.
- [6] W. Lan, J. Dang, Y. Wang, and S. Wang, "Pedestrian detection based on yolo network model," in 2018 IEEE international conference on mechatronics and automation (ICMA), pp. 1547–1551, IEEE, 2018.
- [7] ] A. Benjumea, I. Teeti, F. Cuzzolin, and A. Bradley, "Yolo-z: Improving small object detection in yolov5 for autonomous vehicles," arXiv preprint arXiv:2112.11798, 2021.
- [8] N. M. A. A. Dazlee, S. A. Khalil, S. Abdul-Rahman, and S. Mutalib, "Object detection for autonomous vehicles with sensor-based technology using yolo," International Journal of Intelligent Systems and Applications in Engineering, vol. 10, no. 1, pp. 129–134, 2022.
- [9] S. Liang, H. Wu, L. Zhen, Q. Hua, S. Garg, G. Kaddoum, M. M. Hassan, and K. Yu, "Edge yolo: Real-time intelligent object detection system based on edge-cloud cooperation in autonomous vehicles," IEEE Transactions on Intelligent Transportation Systems, vol. 23, no. 12, pp. 25345–25360, 2022.
- [10] M. Lippi, N. Bonucci, R. F. Carpio, M. Contarini, S. Speranza, and A. Gasparri, "A yolo-based pest detection system for precision agriculture," in 2021 29th Mediterranean Conference on Control and Automation (MED), pp. 342–347, IEEE, 2021.
- [11] W. Chen, H. Huang, S. Peng, C. Zhou, and C. Zhang, "Yolo-face: a real-time face detector," The Visual Computer, vol. 37, pp. 805–813, 2021.
- [12] . Viola and Jones, "Robust Real-time Object Detection", IJCV 2001











45.98



IMPACT FACTOR: 7.129







# INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Call : 08813907089 🕓 (24\*7 Support on Whatsapp)