

ISSN No. : 2321-9653



International Journal for Research in Applied Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com



JISRA F

ISRA Journal Impact Factor: **7.429**





THOMSON REUTERS Researcher ID: N-9681-2016



TOGETHER WE REACH THE GOAL SJIF 7.429

It is here by certified that the paper ID : IJRASET64601, entitled Optimization of Motion Planning for Quadrotor-Equipped Robotic Manipulators

> by Melwin Tony V

after review is found suitable and has been published in

Volume 12, Issue XI, November 2024

in



Editor in Chief, **iJRASET**

International Journal for Research in Applied Science & Engineering Technology (International Peer Reviewed and Refereed Journal) Good luck for your future endeavors



ISSN No. : 2321-9653



International Journal for Research in Applied Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com



JISRA F

ISRA Journal Impact Factor: **7.429**





THOMSON REUTERS Researcher ID: N-9681-2016



TOGETHER WE REACH THE GOAL SJIF 7.429

It is here by certified that the paper ID : IJRASET64601, entitled Optimization of Motion Planning for Quadrotor-Equipped Robotic Manipulators

> by Perarasu P

after review is found suitable and has been published in

Volume 12, Issue XI, November 2024

in



Editor in Chief, **iJRASET**

International Journal for Research in Applied Science & Engineering Technology (International Peer Reviewed and Refereed Journal) Good luck for your future endeavors



ISSN No. : 2321-9653



International Journal for Research in Applied Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com



JISRA F

ISRA Journal Impact Factor: **7.429**





THOMSON REUTERS Researcher ID: N-9681-2016



TOGETHER WE REACH THE GOAL SJIF 7.429

It is here by certified that the paper ID : IJRASET64601, entitled Optimization of Motion Planning for Quadrotor-Equipped Robotic Manipulators

> by Dr. Anbarasi MP



Editor in Chief, **iJRASET**

International Journal for Research in Applied Science & Engineering Technology (International Peer Reviewed and Refereed Journal) Good luck for your future endeavors

after review is found suitable and has been published in

Volume 12, Issue XI, November 2024

in